# Olga Pokorná Spinor fields on Riemannian manifolds

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#### SPINOR FIELDS ON RIEMANNIAN MANIFOLDS

### Olga Pokorná<sup>1</sup>

## 1. Introduction

Let (M,g) be a connected Riemannian manifold of dimension n with a spin structure  $(\widetilde{P},\eta)$ , let S be a spinor bundle on M and  $\Gamma(S)$  the space of all smooth sections od S.

A spin field  $\psi \in \Gamma(S)$  is called Killing spinor with a Killing number  $\lambda \in \mathbf{C}$  if the differential equation

$$\nabla_X^S \psi = \lambda X. \psi \tag{1}$$

is satisfied for all vector fields X on M.

A spinor field  $\psi \in \Gamma(S)$  is called a twistor spinor if for all vector fields X on M

$$\mathcal{D}\psi = \nabla_X^S \psi + \frac{1}{n} X. D\psi = 0 \tag{2}$$

and such a field  $\psi$  is called E-spinor (or so-called Lichnerowicz spinor) if for all vectors fields X on the manifold M

$$E\psi = \nabla_X^S(D\psi) + \frac{R}{4(n-1)}X.\psi = 0, \tag{3}$$

where D denotes the Dirac operator.

The equation (3) was introduced by A. Lichnerowicz in 1988 in connection with a study of spinor fields. At the same time he proved the following important theorems (see [4]).

## Theorem 1.1. (Lichnerowicz)

If (M,g) is a connected Riemannian spin manifold of dimension  $n \geq 3$  with a nontrivial E-spinor, then the scalar curvature R is constant on M.

## Theorem 1.2 (Lichnerowicz)

If (M, g) is a compact Riemannian spin manifold with a nontrivial E-spinor, then

$$Ker(\mathcal{D}) = Ker(E) = \mathbf{K},$$

where we denoted by K the space of all Killing spinors on M (see [1], e.g.).

<sup>&</sup>lt;sup>1</sup>This paper is in final form and no version of it will be submitted for publication elsewhere.

I have succeeded in finding E-spinors on  $S^2 \times R^1$  and  $H^2 \times R^1$ . It is a natural way to construct E-spinors which are not Killing ones. Noncompact Riemannian manifolds  $S^2 \times R^1$  and  $H^2 \times R^1$  are not the Einstein spaces and that is why Killing spinors do not exist there.

### Proposition 1.3

Every solution of the equation (3) on  $H^2 \times R^1$  is of the form

$$\psi(x,t) = \{A_0\cos(\frac{1}{2}t) + A_1\sin(\frac{1}{2}t)\}\psi^+(x) + \{A_0\sin(\frac{1}{2}t) - A_1\cos(\frac{1}{2})\}\psi^-(x) +$$
 $+\{B_0\cos(\frac{1}{2}t) + B_1\sin(\frac{1}{2}t)\}\varphi^+(x) + \{-B_0\sin(\frac{1}{2}t) + B_1\cos(\frac{1}{2}t)\}\varphi^-(x),$ 

where  $A_0$ ,  $A_1$ ,  $B_0$ ,  $B_1$  are arbitrary constants and  $\psi = \psi^+ + \psi^-$  resp.  $\varphi = \varphi^+ + \varphi^-$  are Killing spinors on  $H^2$  corresponding to  $\lambda = \frac{i}{2}$  (resp.  $\lambda = -\frac{i}{2}$ ). Proof.(see [5])

## Proposition 1.4

Every solution of the equation (3) on  $S^2 \times R^1$  is of the form

$$\psi(x,t) = \{A_0 \cosh(\frac{1}{2}t) + A_1 \sinh(\frac{1}{2}t)\}\psi^+(x) - i\{A_0 \sinh(\frac{1}{2}t) + A_1 \cosh(\frac{1}{2}t)\}\psi^-(x) + \{B_0 \cosh(\frac{1}{2}t) + B_1 \sinh(\frac{1}{2}t)\}\varphi^+(x) + i\{B_0 \sinh(\frac{1}{2}t) + B_1 \cos(\frac{1}{2}t)\varphi^-(x), \}$$

where  $A_0$ ,  $A_1$ ,  $B_0$ ,  $B_1$  are arbitrary constants and  $\psi = \psi^+ + \psi^-$  resp.  $\varphi = \varphi^+ + \varphi^-$  are Killing spinors on  $S^2$  corresponding to  $\lambda = \frac{1}{2}$  (resp.  $\lambda = \frac{1}{2}$ ). Proof.(see [5])

# 2. The other relations between Ker(E) and Ker(D).

## Theorem 2.1

Let (M,g) be a connected Riemannian manifold of dimension n with a spin structure. If  $\psi \in Ker(E) \neq \{0\}$ , then

$$R^{S}(X,Y).D\psi + \frac{R}{4(n-1)}\left(Y.\nabla_{X}^{S}\psi - X.\nabla_{Y}^{S}\psi\right) = 0, \tag{4}$$

where  $R^S(X,Y)$  is the curvature tensor of the connection  $\nabla^S$  on S and X,Y are vector fields on M.

*Proof:* If  $\psi \in Ker(E) \neq \{0\}$ , then the Theorem 1.1 implies that the scalar curvature R is constant on M (see [4]).

By differentiation of the equation (3) with respect to Y, we get

$$\nabla_Y^S \nabla_X^S (D\psi) + \frac{R}{4(n-1)} (\nabla_Y^S X) \cdot \psi + \frac{R}{4(n-1)} X \cdot \nabla_Y^S \psi = 0.$$
 (5)

Exchanging X and Y, we get

$$\nabla_X^S \nabla_Y^S (D\psi) + \frac{R}{4(n-1)} (\nabla_X^S Y) \cdot \psi + \frac{R}{4(n-1)} Y \cdot \nabla_X^S \psi = 0.$$
 (6)

The equation (3) is also valid for vector fields [X, Y] on M:

$$\nabla^{S}_{[X,Y]}(D\psi) + \frac{R}{4(n-1)}[X,Y].\psi = 0. \tag{7}$$

By subtracting the equations (5) and (7) from (6), we get

$$\begin{split} \nabla_X^S \nabla_Y^S (D\psi) - \nabla_Y^S \nabla_X^S (D\psi) - \nabla_{[X,Y]}^S (D\psi) + \\ + \frac{R}{4(n-1)} (\nabla_X^S Y - \nabla_Y^S X - [X,Y]) \psi + \\ + \frac{R}{4(n-1)} (Y \cdot \nabla_X^S \psi - X \cdot \nabla_Y^S \psi) = 0. \end{split}$$

For a given  $\psi \in \Gamma(S)$ , let us define functions

$$C\psi = Re(D\psi, \psi)$$

$$Q\psi = |\psi|^2 |D\psi|^2 - C^2 \psi - \sum_{i=1}^n (Re(D\psi, e_i \psi))^2$$

Then we have

## Theorem 2.2

Let (M,g) be a connected Riemannian spin manifold of dimension  $n \geq 3$  such that  $Ker(E) \neq 0$  and the scalar curvature is nonzero. Then the quadratic forms C and Q are constant on Ker(E).

**Proof:** Theorem 1.1 implies that the scalar curvature R is constant. Moreover R is nonzero. Then Corollary of Theorem 1 (see[2]) implies that,

$$\dim_C \! Ker(E) = \dim_C \! Ker(\mathcal{D}) \leq 2^{[n/2]+1}.$$

On this vector space, there exist quadratic forms C and Q.

For all  $X \in T_xM$ ,  $x \in M$  we get

$$X(C\psi) = Re((\nabla_X^S D\psi, \psi) + (D\psi, \nabla_X^S \psi)). \tag{8}$$

Proposition 2 (see [2]) implies, that

$$abla_X^S \psi = rac{2(n-1)}{R(n-2)} \left(rac{R}{2(n-1)}X - Ric(X)
ight).D\psi.$$

We obtain

$$\begin{split} X(C\psi) &= \operatorname{Re}\left(-\frac{R}{4(n-1)}X.\psi,\psi\right) + \operatorname{Re}\left(D\psi,\frac{2(n-1)}{R(n-2)}\left(\frac{R}{2(n-1)}X - \operatorname{Ric}(X)\right).D\psi\right) = \\ &= -\frac{R}{4(n-1)}\operatorname{Re}(X.\psi,\psi) + \frac{2(n-1)}{R(n-2)}.\operatorname{Re}\left(D\psi,\left(\frac{R}{2(n-1)}X - \operatorname{Ric}(X)\right).D\psi\right). \end{split}$$

Clifford multiplication has the following property with respect to the Hermetian scalar product  $(\ ,\ )$ 

$$\operatorname{Re}(X\psi,\psi)=0 \quad \text{for all} \quad X\in T_xM, x\in M$$

hence  $C\psi = \text{konst.}$ 

Moreover, if  $\psi \in Ker(E)$ , then Theorem 1 (see [2]) implies that

$$\varphi = D\psi \in Ker(\mathcal{D})$$

hence  $Q\varphi = \text{konst (see [3])}$ .

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$$egin{aligned} Q arphi &= |arphi|^2 |D arphi|^2 - C^2 arphi - \sum_{i=1}^n (\operatorname{Re}(D arphi, e_i. arphi))^2 = \ &= |D \psi|^2 |D^2 \psi|^2 - (\operatorname{Re}(D^2 \psi, D \psi))^2 - \sum_{i=1}^n (\operatorname{Re}(D^2 \psi, e_i. D \psi))^2 = \ &= rac{n^2 R^2}{16(n-1)^2} (|D \psi|^2 |\psi|^2 - (\operatorname{Re}(\psi, D \psi))^2 - \sum_{i=1}^n (\operatorname{Re}(\psi, e_i. D \psi))^2 = \ &= \left(rac{n R}{4(n-1)}
ight)^2 Q \psi. \end{aligned}$$

Moreover we have

$$\operatorname{Re}(\psi, e_i.D\psi) = -\operatorname{Re}(D\psi, e_i.\psi).$$

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Hence  $Q\psi$  is constant.

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